

FIG-1

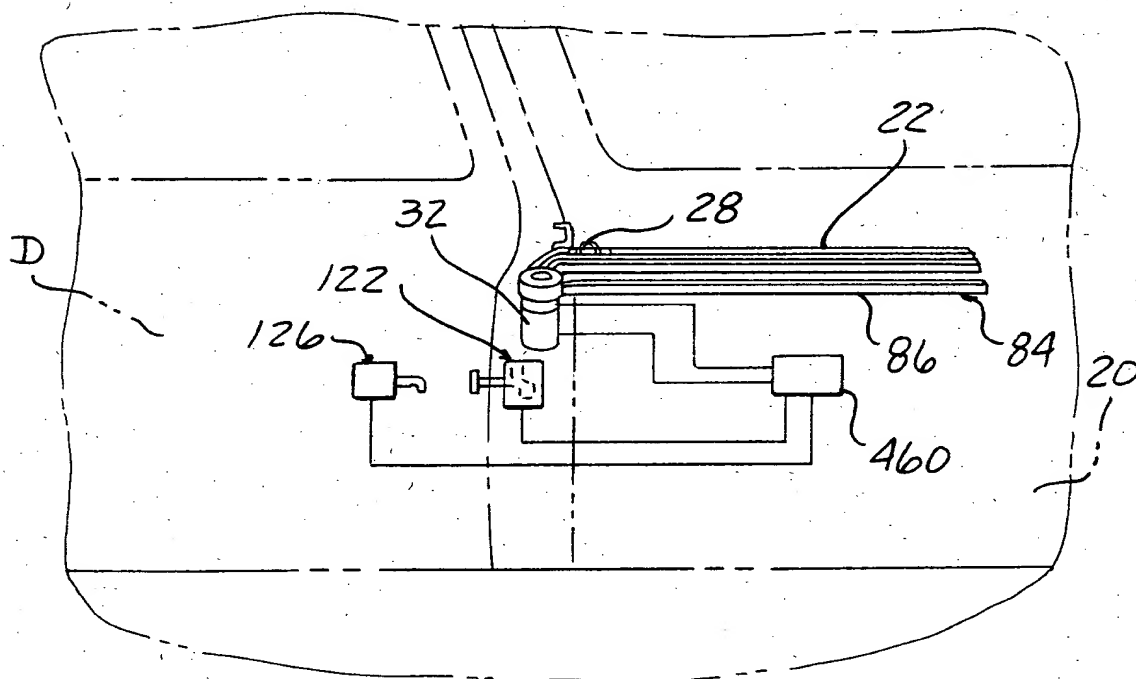


FIG- 3

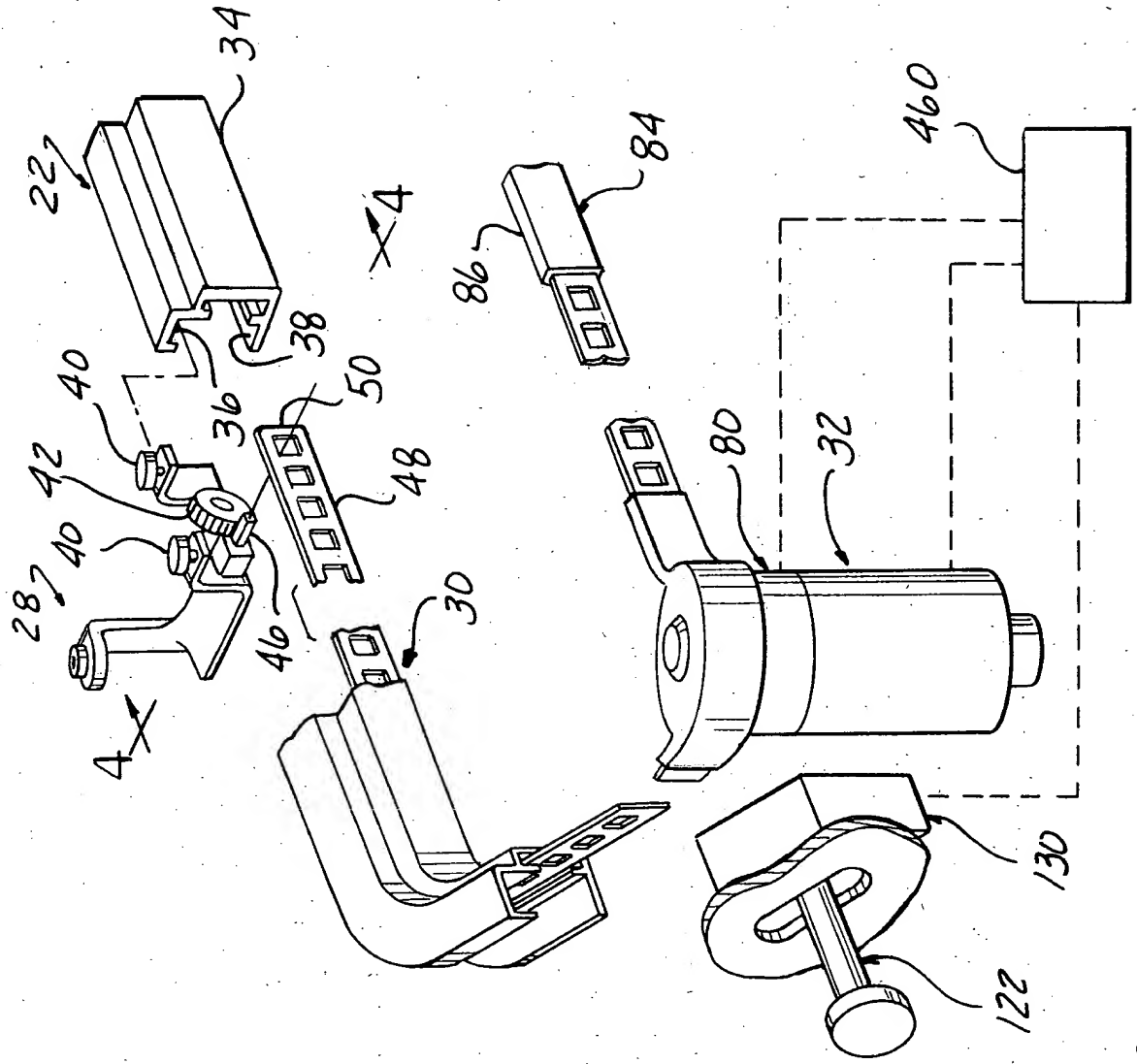


FIG-2

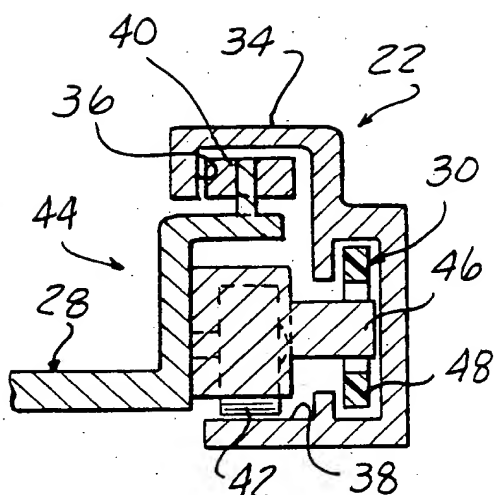


FIG - 4

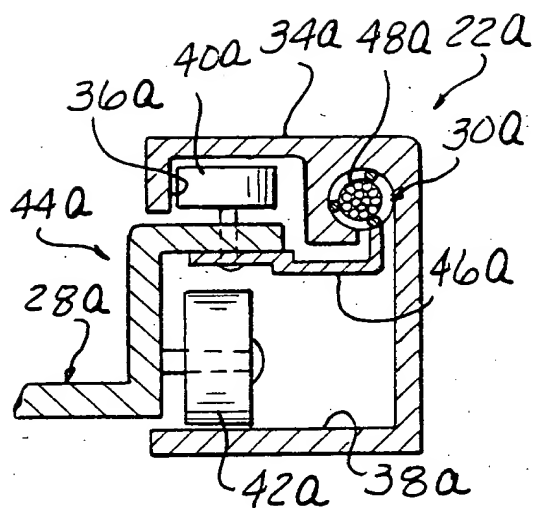


FIG-5

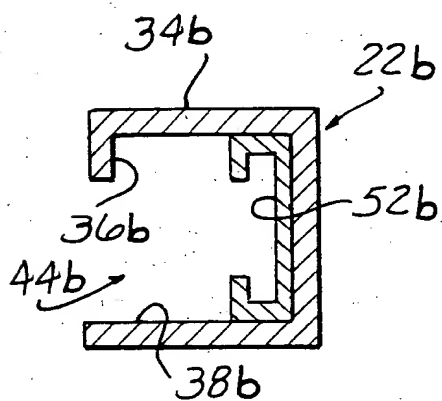


FIG-6

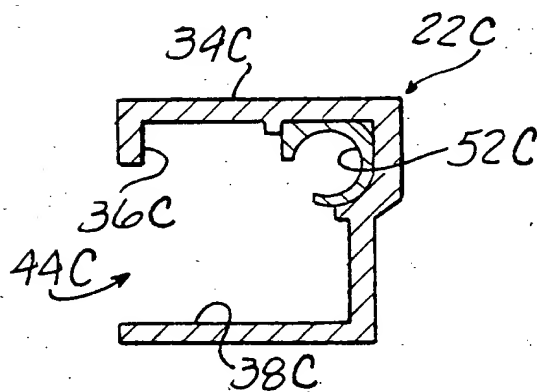


FIG - 7

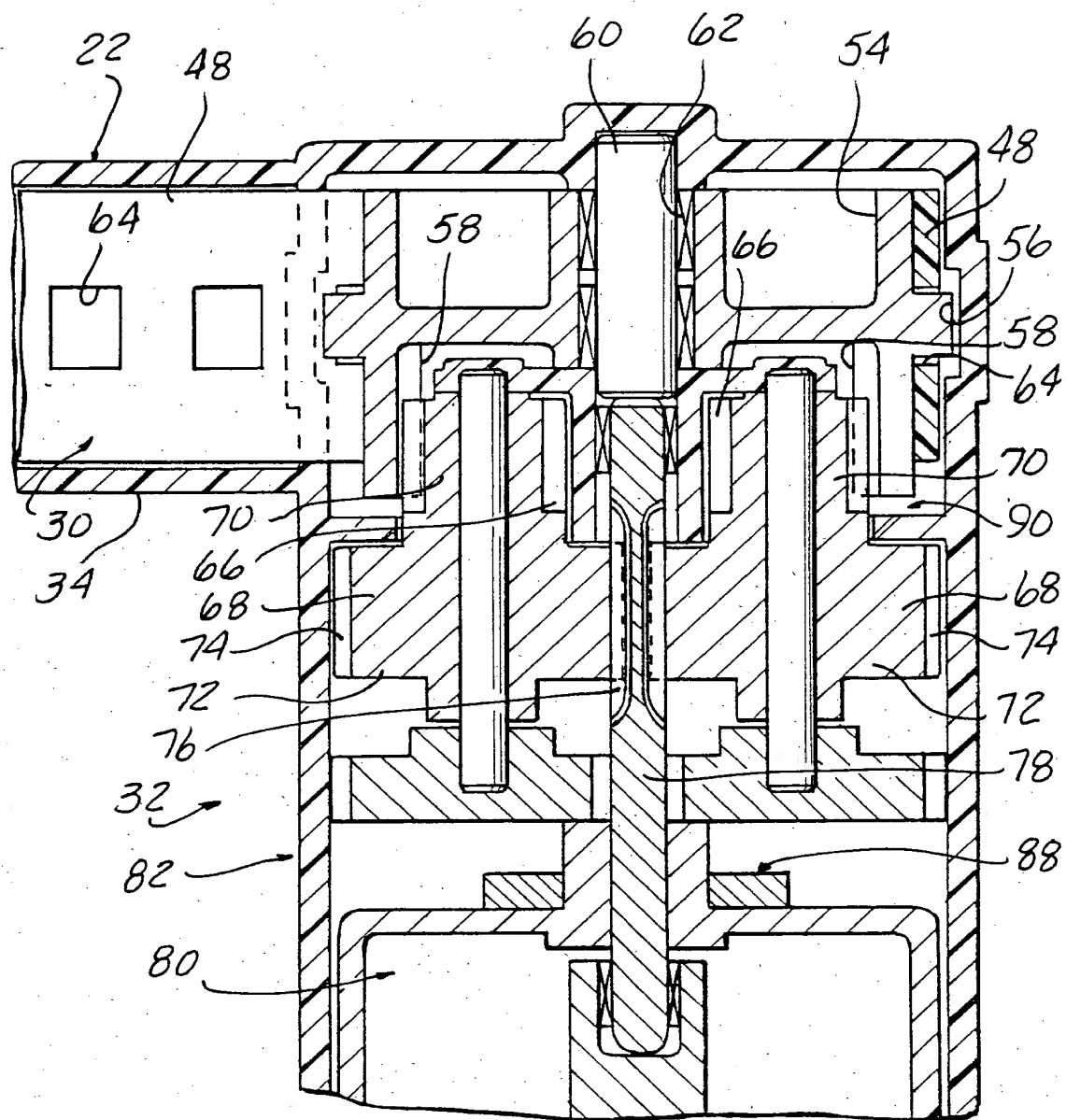


FIG - 8

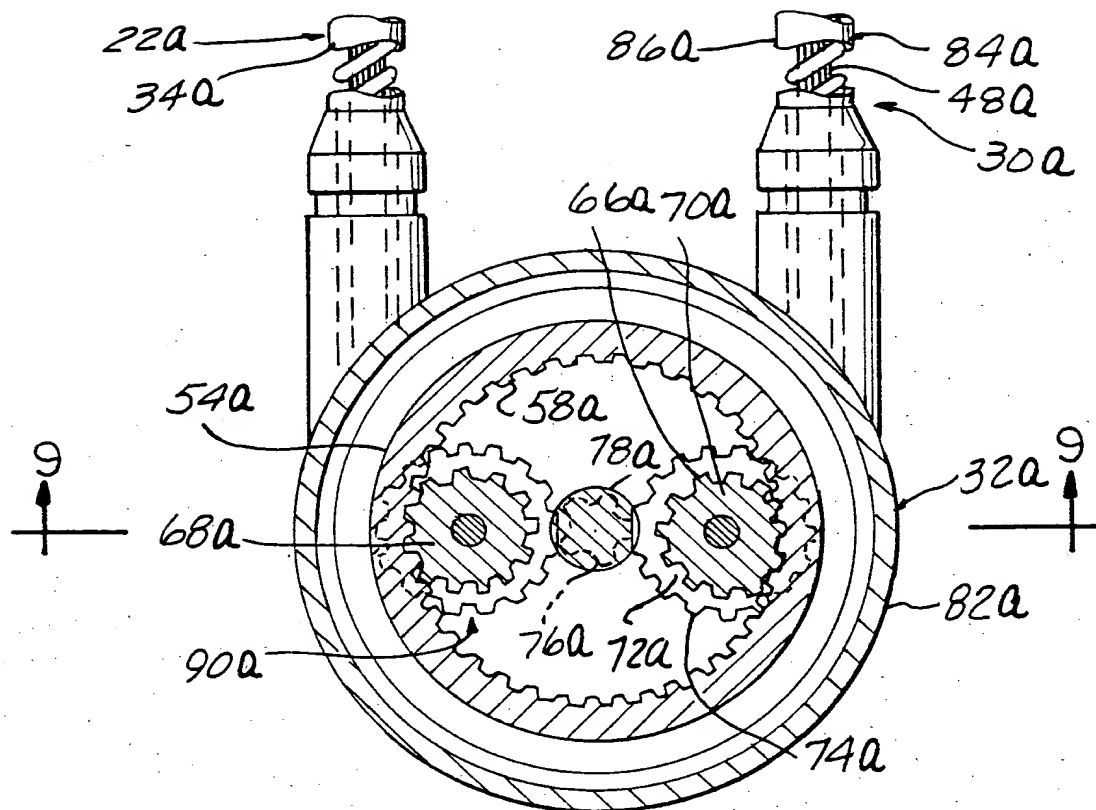


FIG-10

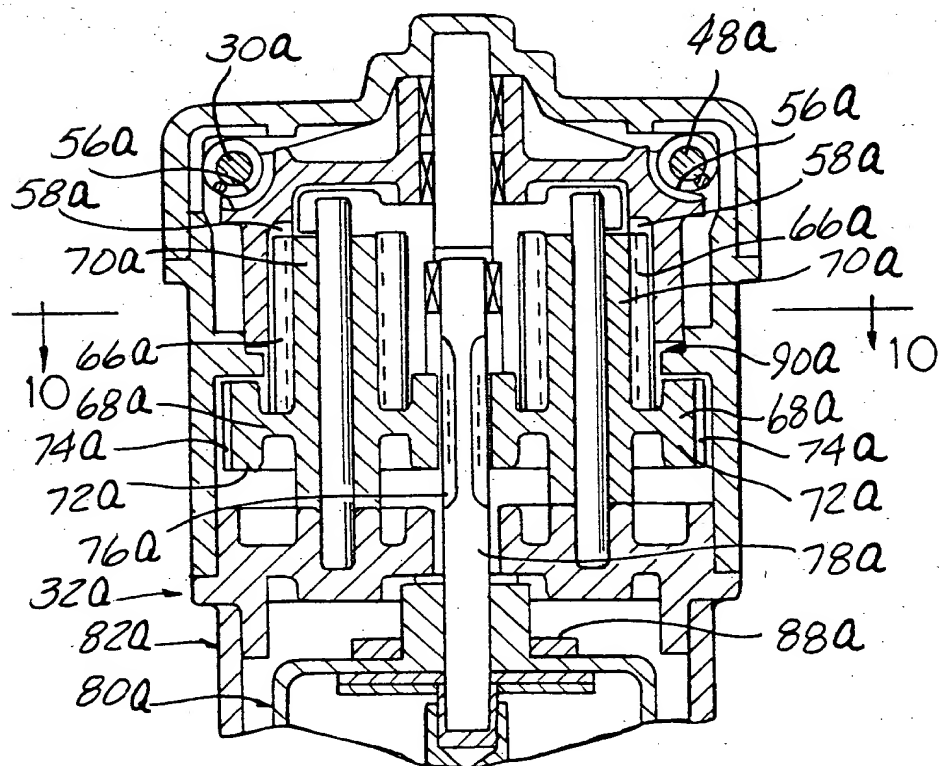


FIG-9

FIG - 11

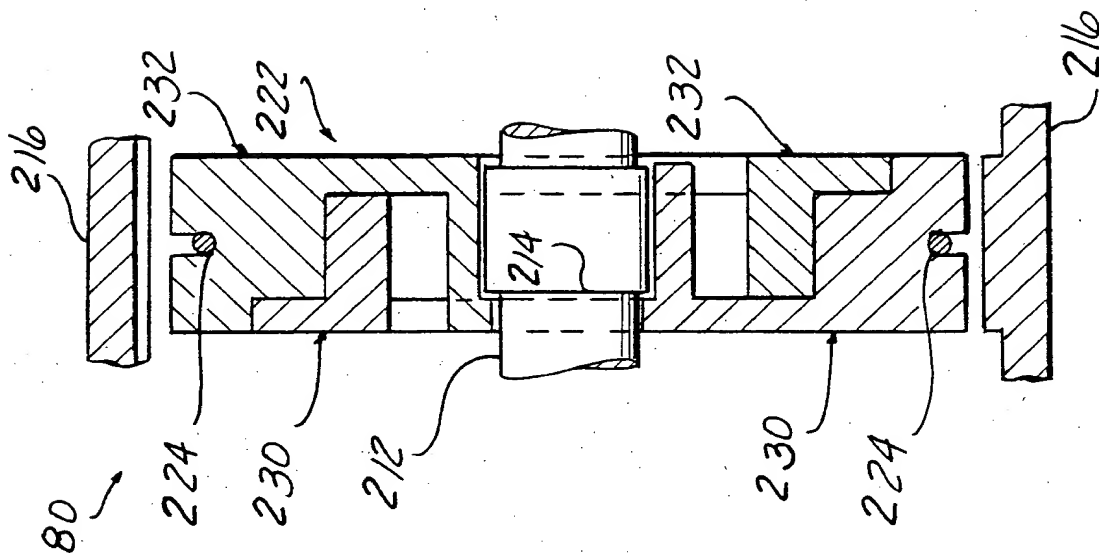


FIG-12

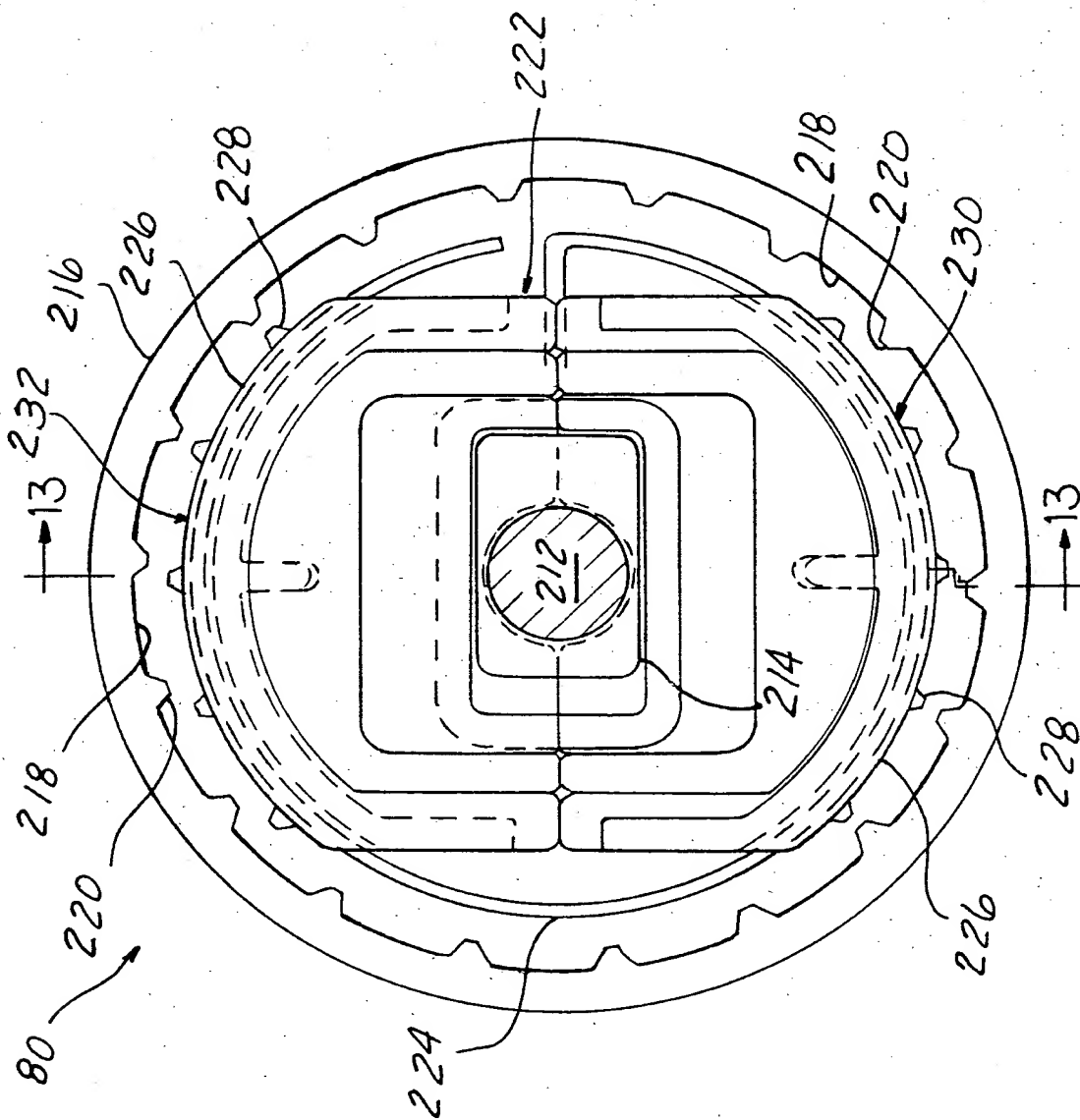


FIG-13

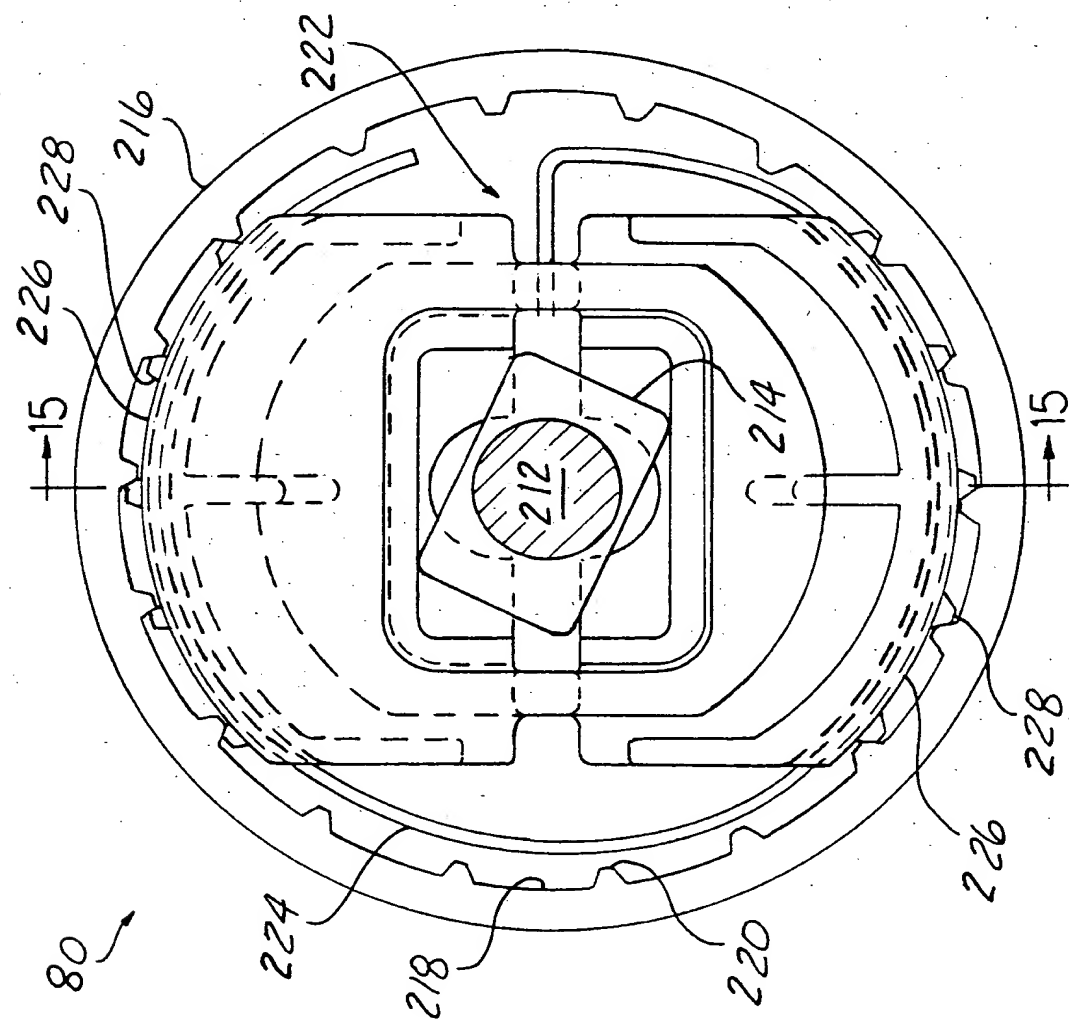


FIG-14

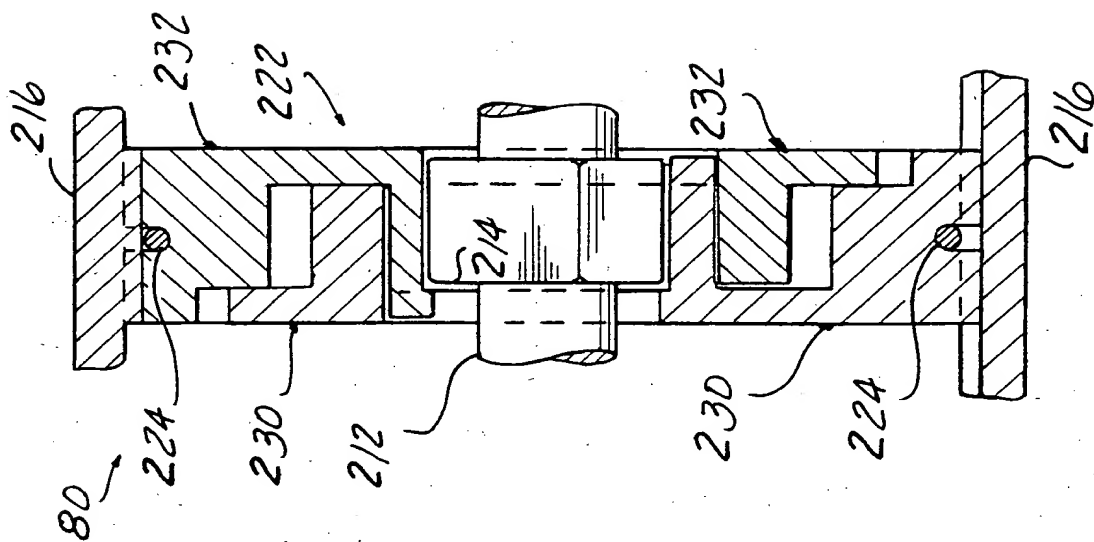


FIG-15



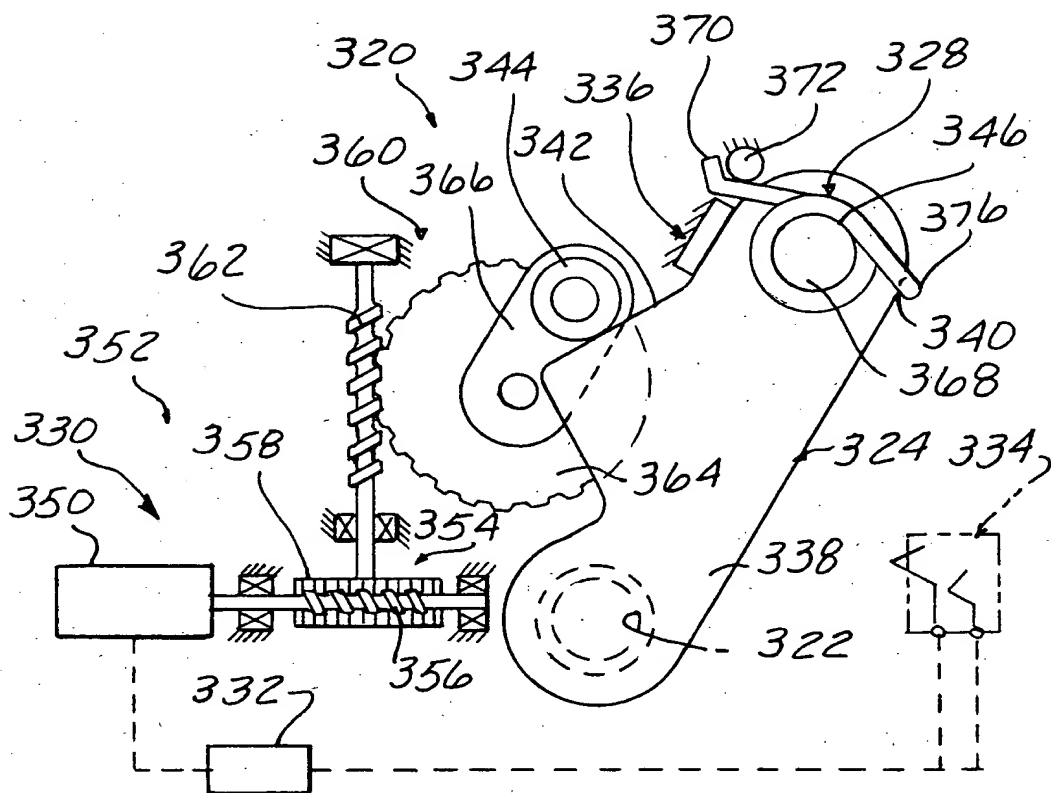


FIG - 16

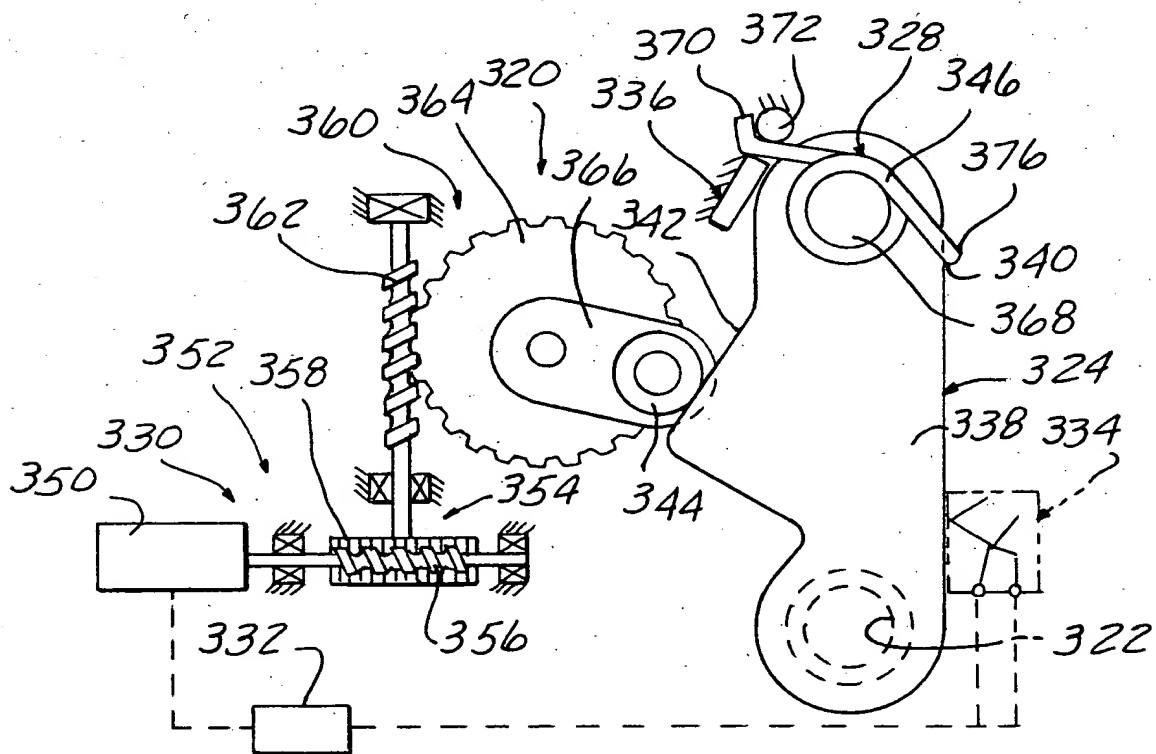
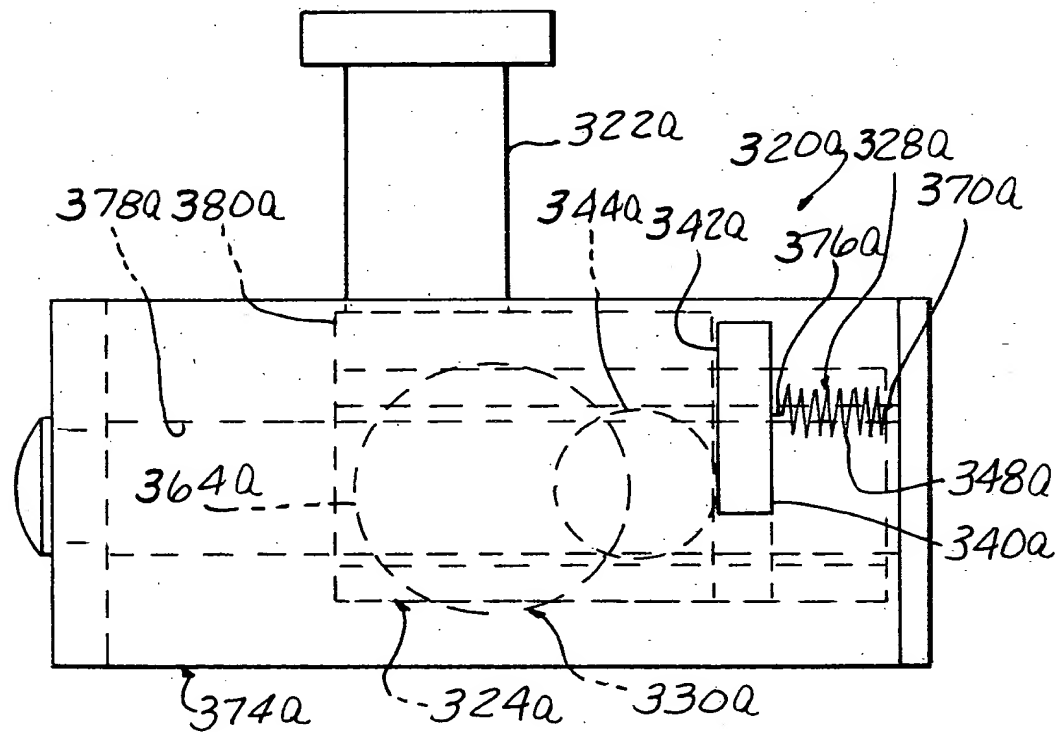
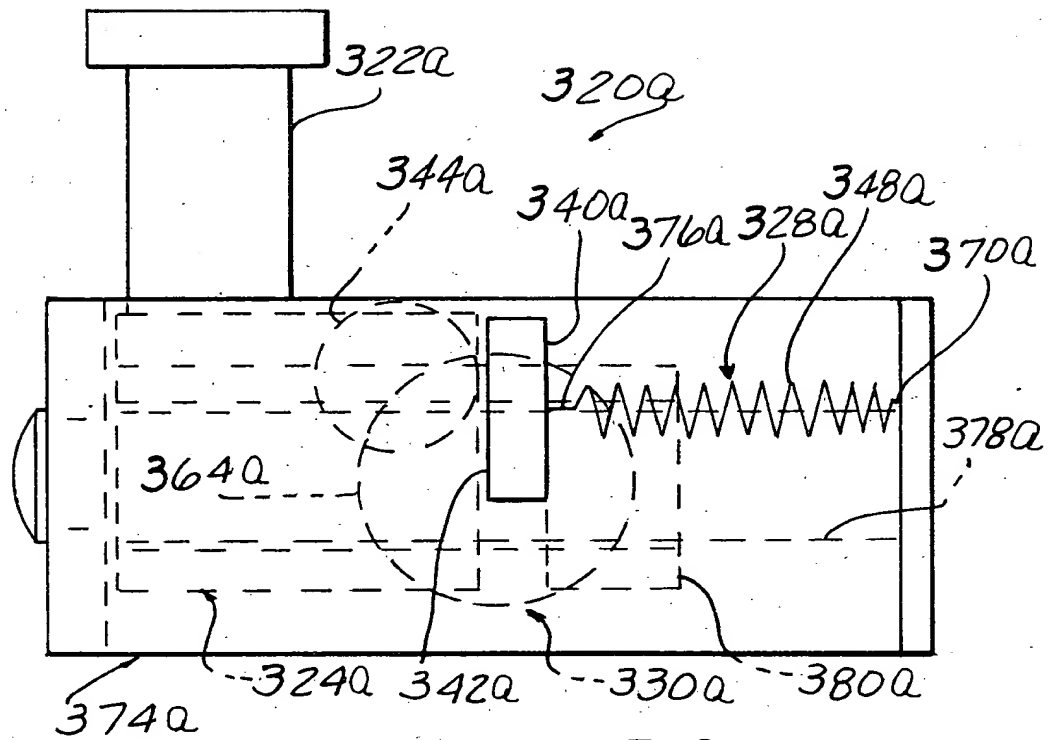


FIG - 17



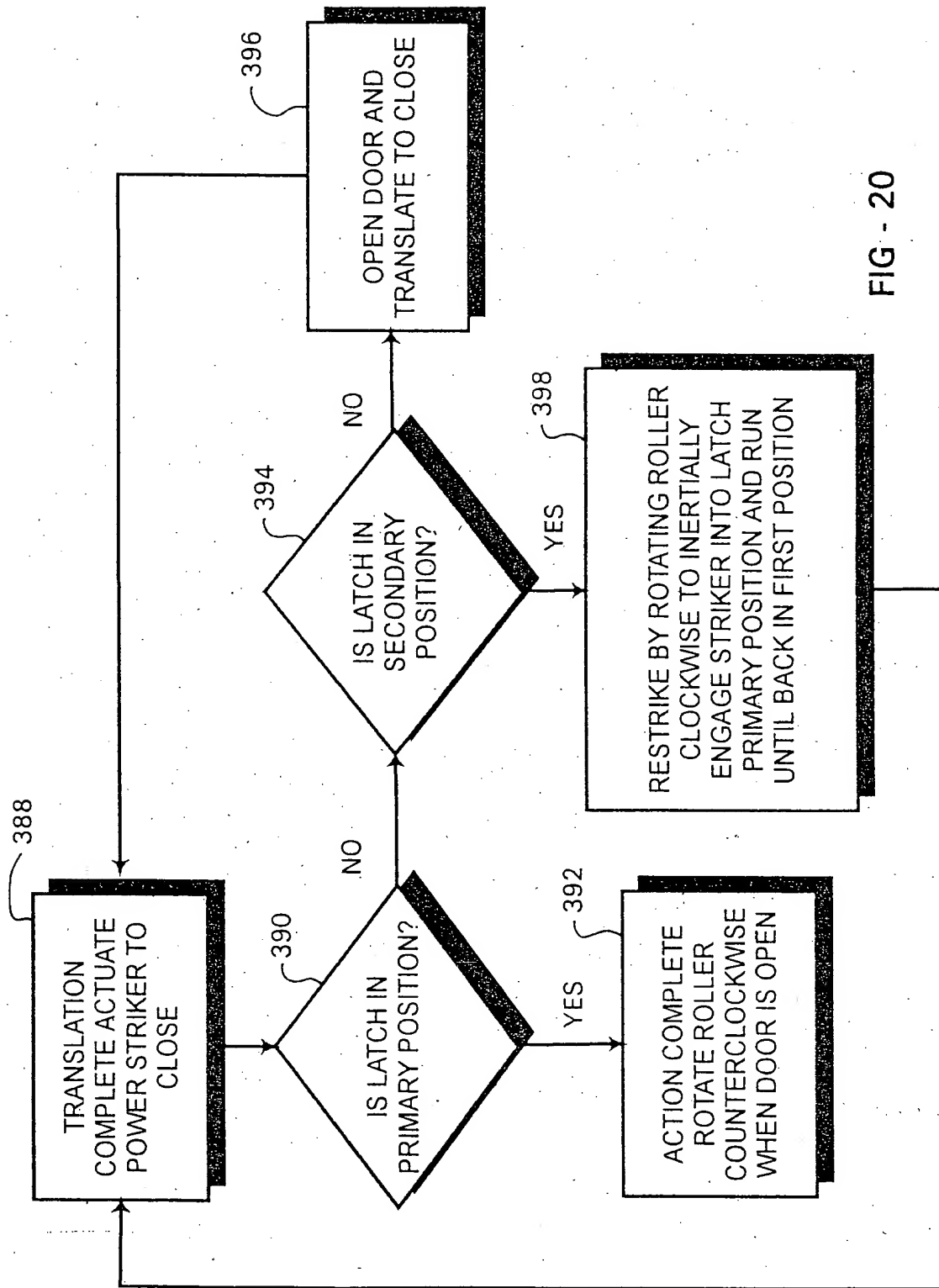


FIG - 20

FIG - 21A

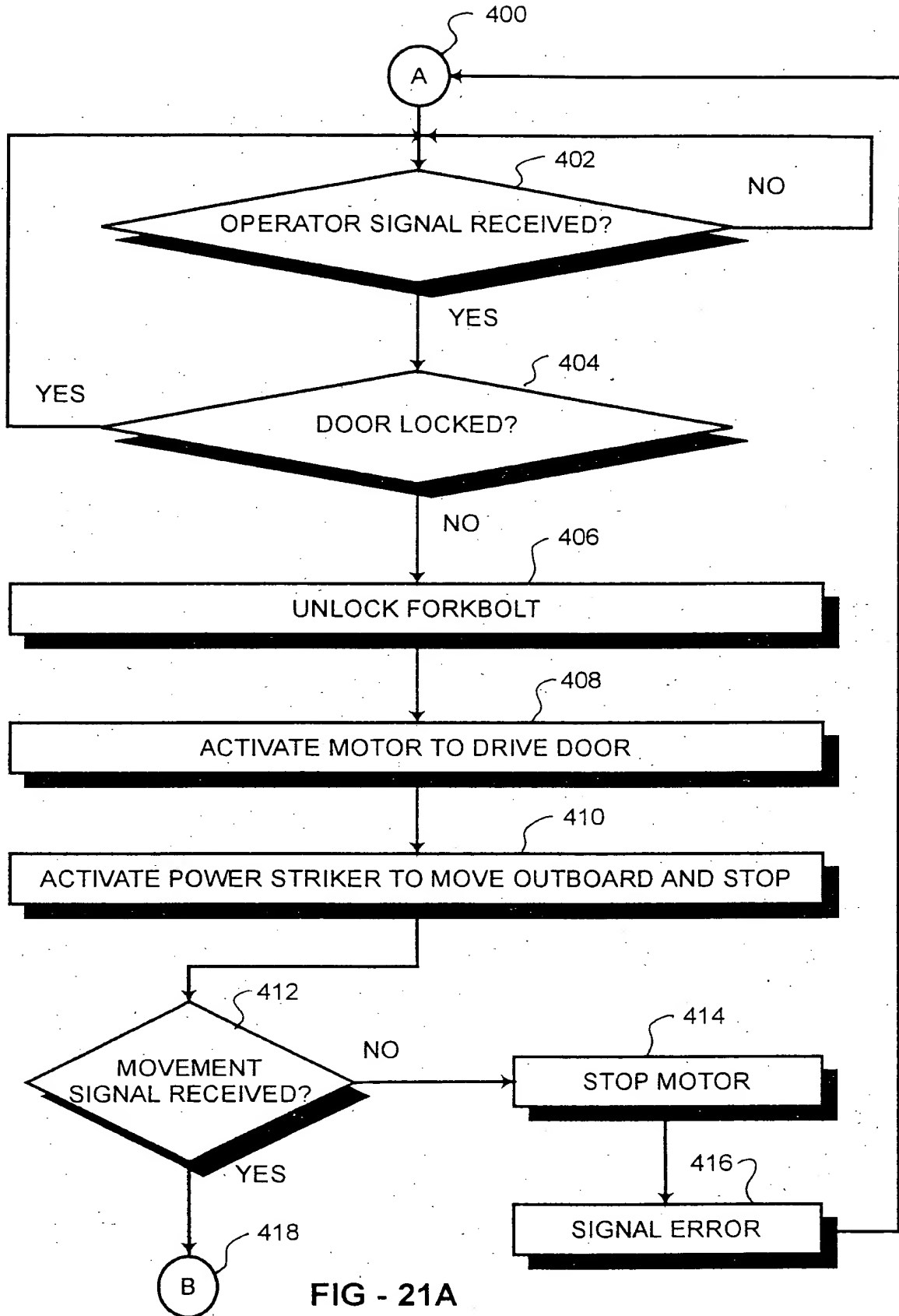


FIG - 21A

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graph TD
    418((B)) --> 420{SIGNAL < MINIMUM VALUE?}
    420 -- YES --> 422[STOP MOTOR AND SIGNAL ERROR]
    422 --> 400((A))
    420 -- NO --> 424[COMPARE SIGNAL TO PREDETERMINED VALUE]
    424 --> 425{IS MOTION DISTANCE < 10 MM?}
    425 -- YES --> 426{BELOW PREDETERMINED VALUE?}
    425 -- NO --> 436[CONTINUE MOVEMENT]
    426 -- YES --> 428[INCREASE MOTOR SPEED]
    426 -- NO --> 430{ABOVE PREDETERMINED VALUE?}
    430 -- YES --> 432[DECREASE MOTOR SPEED]
    430 -- NO --> 434{APPROACHING END LIMIT?}
    428 --> 436
    432 --> 436
    434 -- NO --> 436
    434 -- YES --> 438{END LIMIT REACHED?}
    436 --> 440[DEACTIVATE MOTOR]
    438 -- NO --> 436
    438 -- YES --> 440
    440 --> 442((C))
    442 --> 418

```

**FIG - 21B**

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graph TD
    442((C)) --> 444{LATCH AND SEAT DOOR?}
    444 -- NO --> 400((A))
    444 -- YES --> 446[LATCH DOOR]
    446 --> 448[ACTIVATE POWER STRIKER TO MOVE INBOARD]
    448 --> 450{DOOR SEATED?}
    450 -- YES --> 400
    450 -- NO --> 452[RELEASE POWER STRIKER TO OUTBOARD POSITION]
    452 --> 454{FLAG SET?}
    454 -- YES --> 456[SIGNAL ERROR AND RESET FLAG]
    456 --> 400
    454 -- NO --> 458[SET FLAG]
    458 --> 448

```

**FIG - 21C**

FIG - 21C

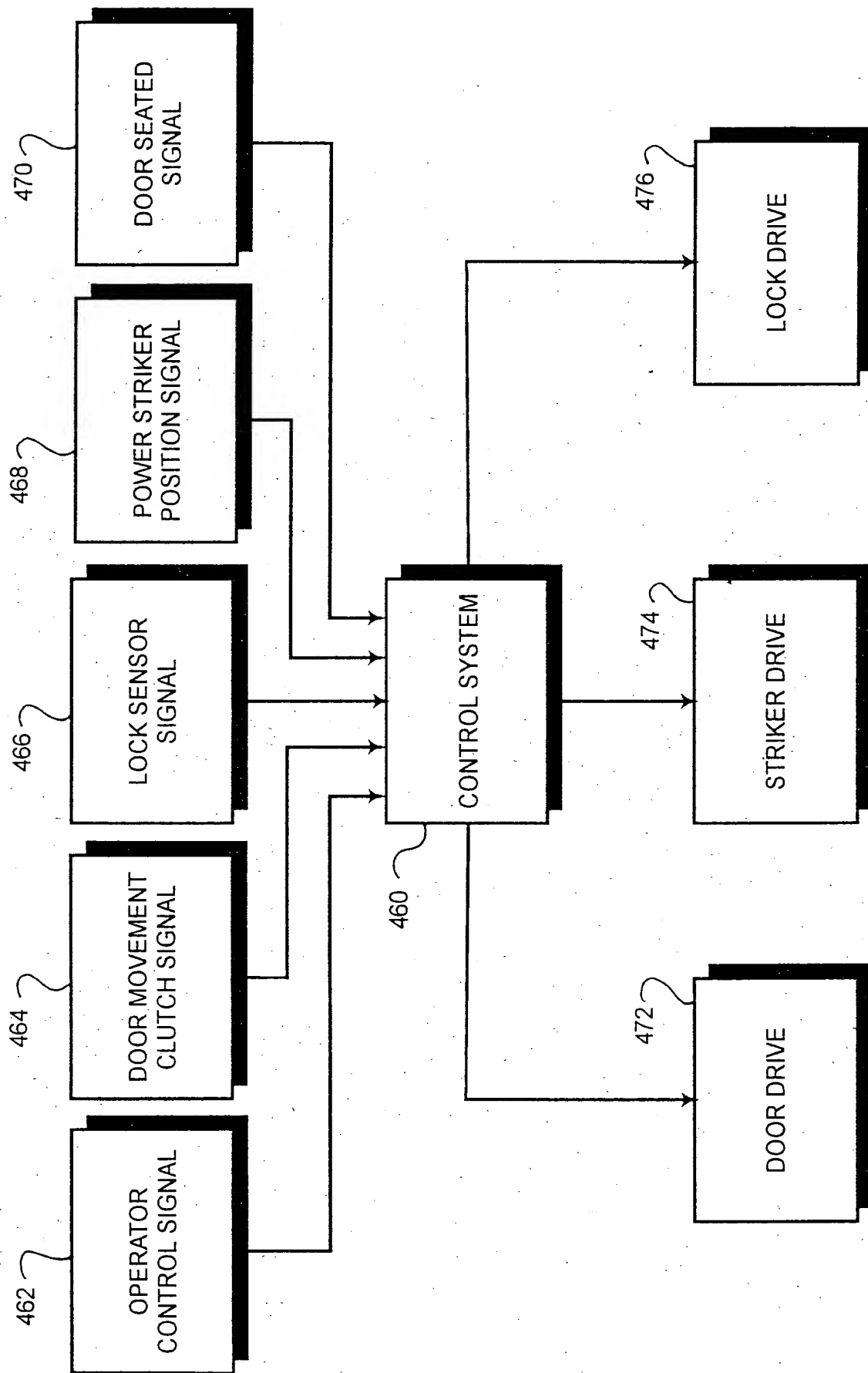


FIG - 22

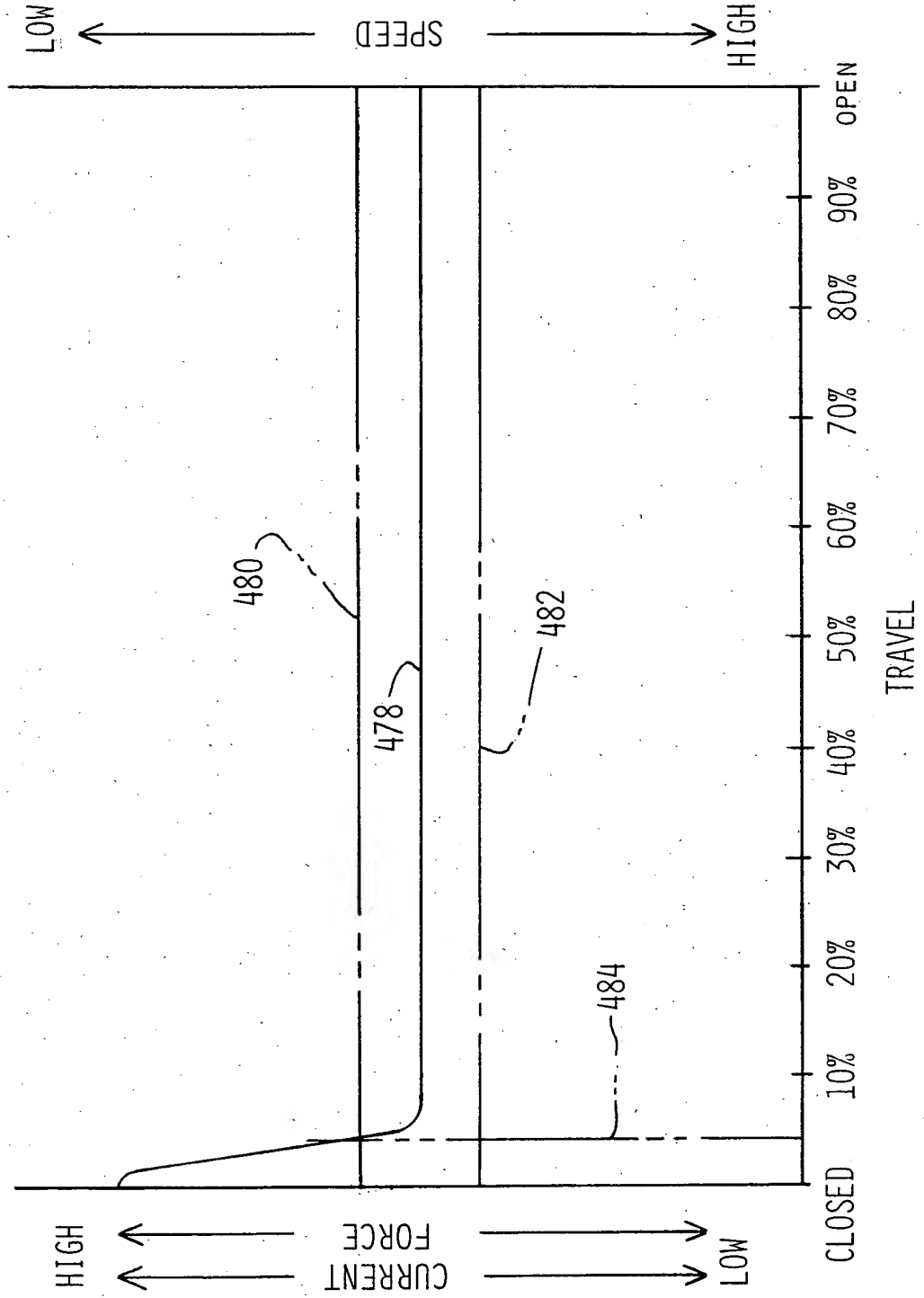


FIG - 23



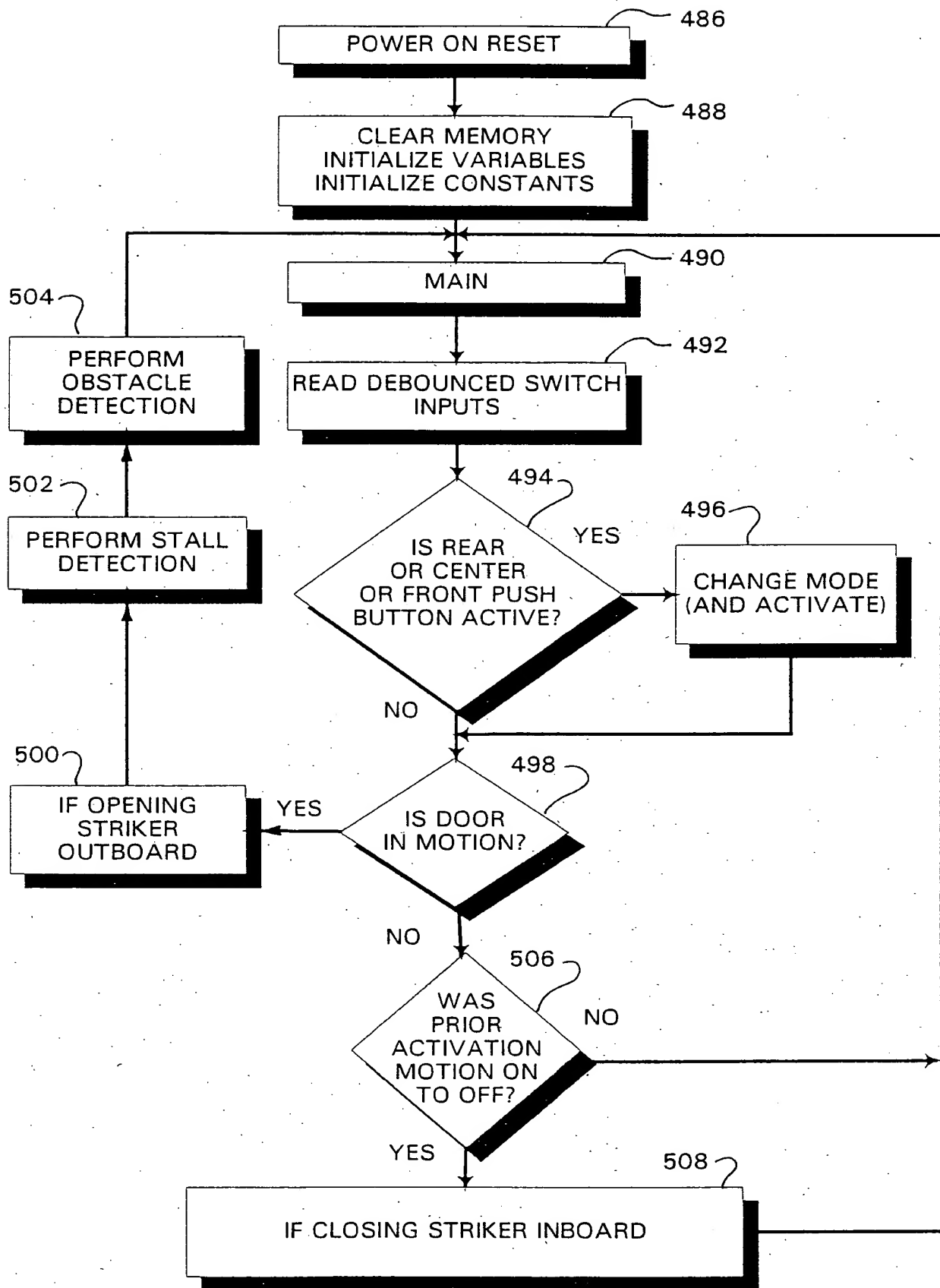


FIG - 24

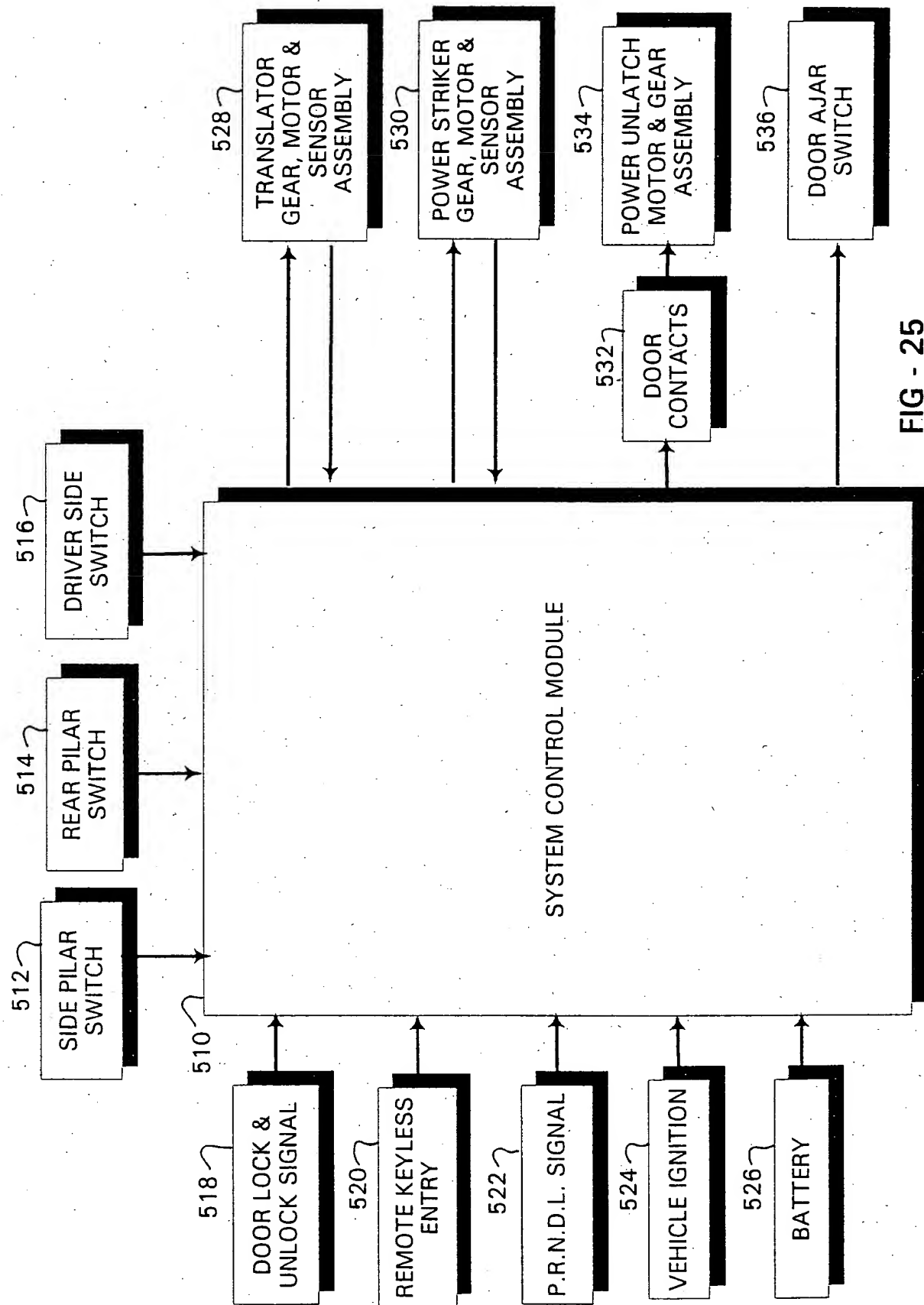


FIG - 25